

Fig. 1

Original Frames:

I0 B1 B2 P3 B4 B5 P6 B7 B8 P9 B10 B11 I12 B13 B14 P15 B16 B17 P18 B19 B20 P21 B22 B23 I24

1)		I12				
2)		I12	P15	P18		
3)		I12	P15	P18	P21	I24
4)		I12	P15	P18	P21	B23 I24
5)		I12	P15	P18	P21	B23 I24
6)		I12	P15	P18	P21 B22	B23 I24
7)		I12	P15	P18	P21 B22	B23 I24
8) I0		I12	P15	P18	P21 B22	B23 I24
9) I0		I12	P15	P18	B20 P21 B22	
10) I0		I12	P15	P18 B19	B20 P21	
11) I0 P3		I12	P15	P18 B19	B20 P21	
12) I0 P3		I12	P15	B17 P18	P19	
13) I0 P3		I12	P15 B16	B17 P18		
14) I0 P3 P6		I12	P15 B16 B17	P18		
15) I0 P3 P6		I12	B14 P15 B16			
16) I0 P3 P6		I12 B13	B14 P15			
17) I0 P3 P6 P9		I12 B13 B14 P15				
18) I0 P3 P6 P9		B11 I12 B13				

114 → Reconstruct Frames
from lost preceding
frame

115 → Utilized at least 7
frame Buffers
During Reconstruction

116 → Display Reconstructed
Data in Reverse Order

117 → Reconstruct
Single frame
Reverse.

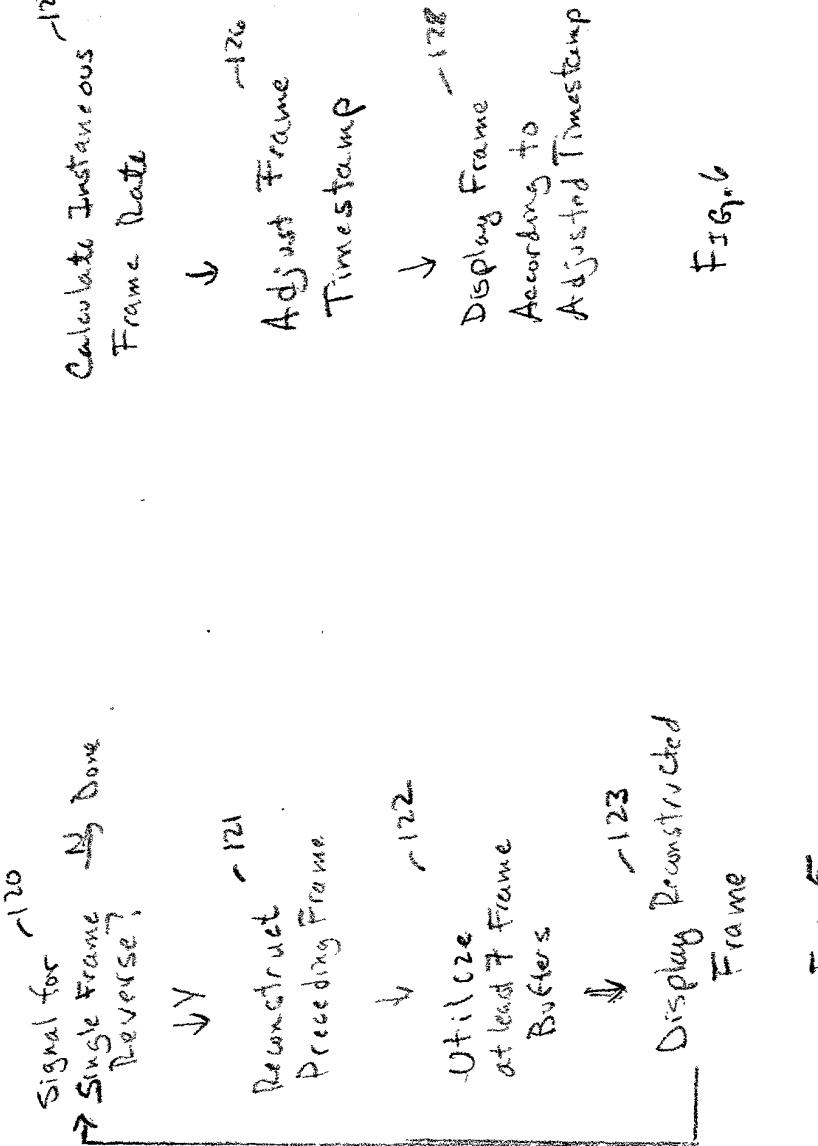


FIG. 3

FIG. 5

FIG. 6